

Aide Mémoire

Subject: Useful formulas for sediment transport and morphology in rivers and channels

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1. General basic equations

Three-dimensional (3D):

The general 3D mass-balance equations for a unit volume of 2-phase (fluid and sediment) flow (after time-averaging of turbulence and applying the eddy-viscosity concept) are :

For fluid:

$$\begin{aligned} \frac{\partial(1-c_s)}{\partial t} + \frac{\partial u(1-c_s)}{\partial x} + \frac{\partial v(1-c_s)}{\partial y} + \frac{\partial w(1-c_s)}{\partial z} + \\ + \frac{\partial}{\partial x} \left[\epsilon_{fx} \frac{\partial c_s}{\partial x} \right] + \frac{\partial}{\partial y} \left[\epsilon_{fy} \frac{\partial c_s}{\partial y} \right] + \frac{\partial}{\partial z} \left[\epsilon_{fz} \frac{\partial c_s}{\partial z} \right] = 0 \end{aligned} \quad (1)$$

For sediment (convection-diffusion equation):

$$\begin{aligned} \frac{\partial c_s}{\partial t} + \frac{\partial uc_s}{\partial x} + \frac{\partial vc_s}{\partial y} + \frac{\partial (w-w_s)c_s}{\partial z} + \\ - \frac{\partial}{\partial x} \left[\epsilon_{sx} \frac{\partial c_s}{\partial x} \right] - \frac{\partial}{\partial y} \left[\epsilon_{sy} \frac{\partial c_s}{\partial y} \right] - \frac{\partial}{\partial z} \left[\epsilon_{sz} \frac{\partial c_s}{\partial z} \right] = 0 \end{aligned} \quad (2)$$

where:

c_s	=	local mean sediment volume concentration (suspension)
u, v, w	=	fluid-velocity in x,y,z-direction
w_s	=	fall velocity of sediment particles
$\epsilon_{fx}, \epsilon_{fy}, \epsilon_{fz}$	=	fluid mixing coefficient in x,y,z-direction
$\epsilon_{sx}, \epsilon_{sy}, \epsilon_{sz}$	=	sediment mixing coefficient in x,y,z-direction (assume $\epsilon_s \approx \epsilon_f$)

Or after rewriting:

$$\begin{aligned} \frac{\partial c_s}{\partial t} + u \frac{\partial c_s}{\partial x} + v \frac{\partial v c_s}{\partial y} + w \frac{\partial c_s}{\partial z} - \frac{\partial}{\partial x} \left[\epsilon_{sx} \frac{\partial c_s}{\partial x} \right] - \frac{\partial}{\partial y} \left[\epsilon_{sy} \frac{\partial c_s}{\partial y} \right] = \\ = w_s (1 - c_s)^\alpha \frac{\partial c_s}{\partial z} + \frac{\partial}{\partial z} \left[\epsilon_{sz} \frac{\partial c_s}{\partial z} \right] \end{aligned} \quad (3)$$

where

α = coefficient used for large concentrations (small concentrations: $\alpha = 1$, else $\alpha \approx 4$ to 5)

Two-dimensional depth-averaged (2DH)

The general 2D continuity equations for sediment, after depth-averaging, become:

Sediment balance:

$$(1 - \epsilon_p) \frac{\partial z_b}{\partial t} + \frac{\partial s_{bx}}{\partial x} + \frac{\partial s_{by}}{\partial y} + \frac{\partial h C_s}{\partial t} + \frac{\partial U h C_s}{\partial x} + \frac{\partial V h C_s}{\partial y} = 0 \quad (4)$$

where:

C_s = depth-averaged suspended sediment concentration
 h = water depth
 s_{bx}, s_{by} = bed-load transport per unit of width in x,y-direction
 U, V = depth-averaged flow velocity in x,y-direction
 ϵ_p = porosity of bed (void volume / total volume) (for sand 0.4 ± 0.05)

Modified Galappatti's equation for suspended sediment:

$$T_a' \frac{\partial C_s}{\partial t} + L_a' U \frac{\partial C_s}{\partial x} + L_a' V \frac{\partial v C_s}{\partial y} = \frac{w_s}{h} (C_{se} - C_s) \quad (5)$$

where:

T_a' = dimensionless adaptation time scale (roughly between 0.5 and 1)
 L_a' = dimensionless adaptation time scale (approximately equal to T_a')
 C_s = depth-averaged equilibrium bed-load concentration
 C_{se} = depth-averaged equilibrium suspended sediment concentration (following from transport equation)

The adaptation time scale can be obtained from the figure below, as function of the ratios w_s/u_* and $u_* / u_* = (\sqrt{g})/C$. Dependent on the type of boundary condition used at the bed for depth-integration a value for T_a' can be selected from the graphs below. The concentration type is more suitable during erosion, while the other works better during sedimentation.

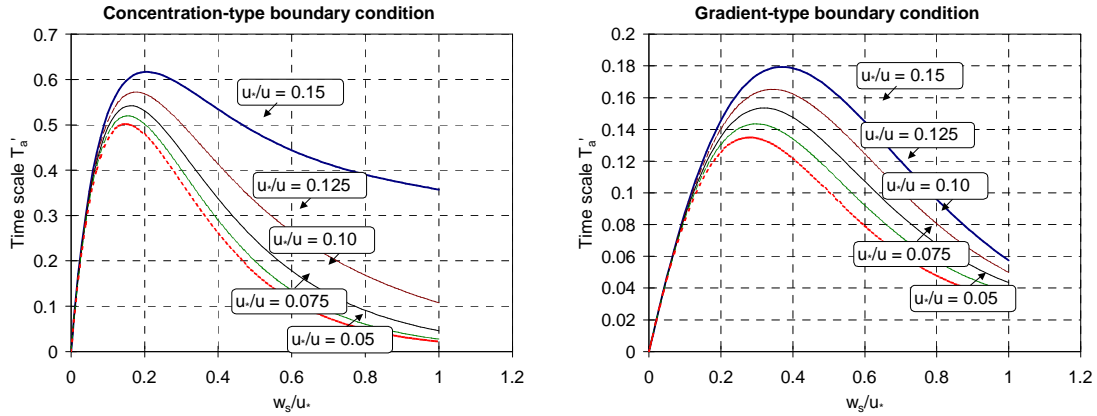


Figure 1 Galappatti's adaptation time-scale for concentration-type boundary condition (left) and gradient-type boundary conditions (right)

One-dimensional cross-sectional averaged (1D)

The one-dimensional basic equation for sediment can be obtained directly from the 2DH equations, resulting in:

$$(1 - \varepsilon_p) \frac{\partial z_b}{\partial t} + \frac{\partial s_{bx}}{\partial x} + \frac{\partial hC_s}{\partial t} + \frac{\partial UhC_s}{\partial x} = 0 \quad (6)$$

And with the original Galappatti's equation for suspended sediment:

$$\frac{\partial C_s}{\partial t} + U \frac{\partial C_s}{\partial x} = \frac{w_s}{T'_a h} (C_{se} - C_s) \quad (7)$$

Time scale T'_a can be obtained from figure 1.

2. Sediment characteristics

Definitions and standards:

- Apply the Phi-size for plotting the sediment size distribution (based on assumption of log-normal distributions):

$$\phi_i = \log_2(D_i) \quad \text{with } D_i \text{ in millimeter} \quad (8)$$

- Mode = most common grain size in the population (with two humps: bimodal mixture)
- Median grain size = D_{50} = grain size for which 50% of the sample is finer.
- Mean grain size = D_m = average grain size of the deposit with $D_m = \sum p_i D_i$
- Sieve diameter: if a particle falls through sieve D_A and remains on next sieve D_B then the sieve diameter $D = (D_A D_B)^{1/2}$. Sieving is used for gravel and sand $> 70 \mu\text{m}$.
- Geometric mean size (first moment of size frequency distribution):

$$1. \quad D_g = \sqrt{D_{84}D_{16}} \tag{9}$$

$$2. \quad D_g = 2^{-\phi_m} \quad \text{with} \quad \phi_m = \sum_{i=1}^N \phi_{mi} P_i$$

where ϕ_m is the arithmetic mean phi-size, ϕ_{mi} is the class middle (in between sieve mesh sizes) of a size fraction, and p_i is probability in size fraction

- Geometric standard deviation (second moment of size frequency distribution; how large is variation around the mean):

$$1. \quad \sigma_g = 0.5 \left(\frac{D_{84}}{D_{50}} + \frac{D_{50}}{D_{16}} \right) \tag{10}$$

$$2. \quad \sigma_g = 2^{\sigma_m} \quad \text{with} \quad \sigma_m = \sum_{i=1}^N (\phi_{mi} - \phi_m)^2 P_i$$

where ϕ_m is the arithmetic mean phi-size (see above), ϕ_{mi} is the class middle (in between sieve mesh sizes) of a size fraction, and p_i is probability in size fraction

- *Specific weight* of a deposit is the density or weight per unit volume, expressed as dry weight or dry density including the pores:

$$\rho_d = (1 - \varepsilon_p) \rho_s \tag{11}$$

with

ε_p = porosity (void volume / total volume) (for sand 0.4 ± 0.05):

ρ_s = specific weight or density of sediment particles (usually order of 2650 kg/m³, quartz)

- *Sediment concentrations* are often expressed in milligrams per liter (C_{mgl} in mg/l) or in parts per million (C_{ppm} in ppm). Conversion formulas:

- If $C_{mgl} < 16,000$ mg/l then: $C_{mgl} = C_{ppm}$ (12)

- If $C_{mgl} > 16,000$ mg/l then: $C_{ppm} = \frac{10^6}{\frac{10^6}{C_{mgl}} + 1 - \frac{1}{\sigma_s}}$ and $C_{mgl} = \frac{10^6}{\frac{10^6}{C_{ppm}} - 1 + \frac{1}{\sigma_s}}$ (13)

In which σ_s is the specific gravity of sediment (in the order of 2.65)

- Grain size classification

Classification according to American Geophysical Union			
Sediment	Millimetres	Sediment	Millimetres
Very large boulders	4096 - 2048	Very coarse sand	2.0 - 1.0
Large boulders	2048 - 1024	Coarse sand	1.0 - 0.5
Medium boulders	1024 - 512	Medium sand	0.5 - 0.25
Small boulders	512 - 256	Fine sand	0.25 - 0.125
Large cobbles	256 - 128	Very fine sand	0.125 - 0.062
Small cobbles	128 - 64	Coarse silt	0.062 - 0.031
Very coarse gravel	64 - 32	Medium silt	0.031 - 0.016
Coarse gravel	32 - 16	Fine silt	0.016 - 0.008
Medium gravel	16 - 8	Very fine silt	0.008 - 0.004
Fine gravel	8 - 4	Coarse clay	0.004 - 0.002
Very fine gravel	4 - 2	Medium clay	0.002 - 0.001
		Fine clay	0.0010 - 0.0005
		Very fine clay	0.0005 - 0.00024

- Fall velocity w_s [m/s] for sediment (van Rijn, 1984)

1. For Stokes range ($Re=w_s D/\nu < 1$ or $D \leq 100 \mu\text{m}$): $w_s = \frac{1}{18} \frac{\Delta g D^2}{\nu}$ (14)

2. For $100 < D \leq 1000 \mu\text{m}$: $w_s = \frac{10\nu}{D} \left(\sqrt{1 + \frac{0.01\Delta g D^3}{\nu^2}} - 1 \right)$ (15)

3. For $D > 1000 \mu\text{m}$: $w_s = 1.1\sqrt{\Delta g D}$ (16)

With

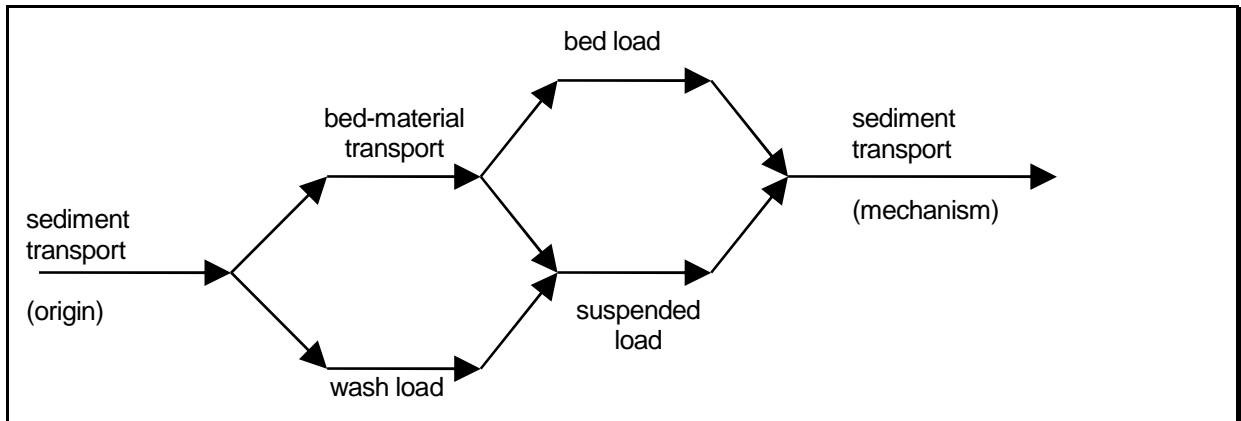
Δ = relative density of sediment, defined as $(\rho_s - \rho_w) / \rho_w$ (usually about 1.65)

ν = kinematic viscosity for clear fluid (usually $1 \cdot 10^{-6} \text{ m}^2/\text{s}$)

3. Sediment transport

Classification

- To study sediment transport processes it is possible to classify the transport processes according to origin and mechanisms as in the following scheme (Jansen et al., 1979):



Shields and initiation of motion (Shields curve)

- The Shields parameter is defined as the ration between flow forces and gravity forces on a sediment particle, and can be expressed as:

$$\theta = \frac{\tau_b}{(\rho_s - \rho)gD} = \frac{u_*^2}{\Delta gD} = \frac{u^2}{C^2 \Delta D} = \frac{h \cdot i}{\Delta D} \quad (17a)$$

where

D	=	characteristic grain size
i	=	slope
u_*	=	shear velocity = $(\tau_b / \rho)^{1/2} = u \cdot g^{1/2} / C$
Δ	=	relative density = $(\rho_s - \rho) / \rho \approx 1.65$ for quartz
ρ	=	density of water $\approx 1000 \text{ kg/m}^3$
ρ_s	=	density of sediment $\approx 1650 \text{ kg/m}^3$ for quartz

- Initiation of motion according to Shields: the threshold for initiation of motion is defined by the critical Shields parameter in the Shields curve. The Shields curve expresses the relation between the Shields parameter θ_c and the grain Reynolds number Re_* , see figure:

$$Re_* = \frac{u_* D}{\nu} \quad ; \quad \theta_c = \frac{\tau_{cr}}{(\rho_s - \rho)gD} = \frac{u_{*,cr}^2}{\Delta gD} \quad (17b)$$

where

Re_*	=	particle Reynolds number
$u_{*,cr}$	=	critical shear velocity = $(\tau_{cr} / \rho)^{1/2}$
Δ	=	relative density = $(\rho_s - \rho) / \rho \approx 1.65$ for quartz
ν	=	kinematic viscosity, usually $1 \cdot 10^{-6} \text{ m}^2/\text{s}$
ρ	=	density of water $\approx 1000 \text{ kg/m}^3$
ρ_s	=	density of sediment $\approx 1650 \text{ kg/m}^3$ for quartz

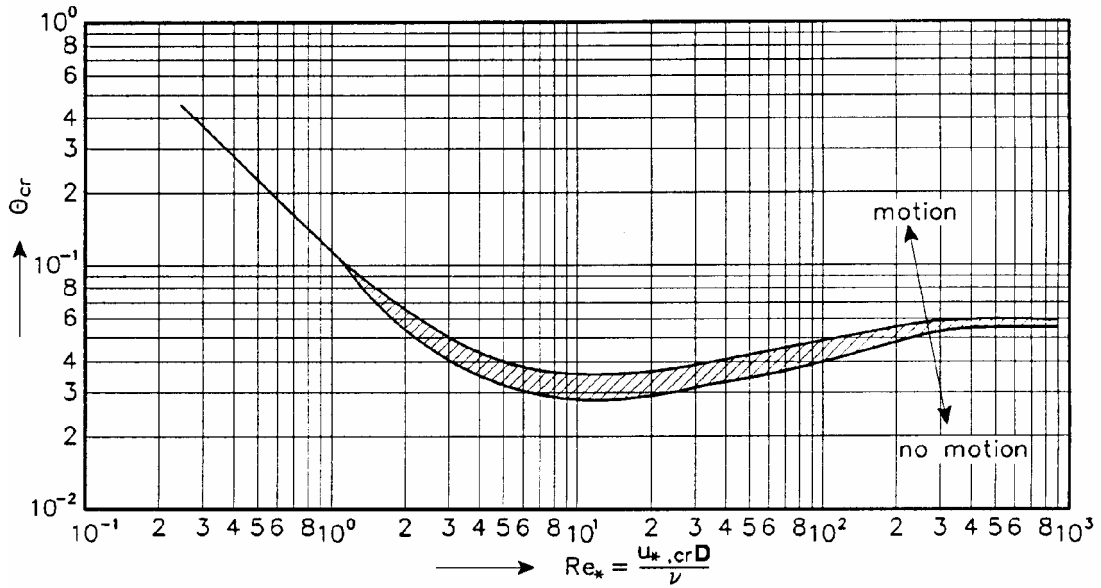


Figure Shields' diagram for initiation of motion (Shields parameter versus grain Reynolds number)

Van Rijn (1984) gives an approximation of the Shields curve as follows:

$$\left. \begin{aligned}
 \theta_{cr} &= \frac{0.24}{D_*} & \text{if } D_* \leq 4 \\
 \theta_{cr} &= \frac{0.14}{D_*^{0.64}} & \text{if } 4 < D_* \leq 10 \\
 \theta_{cr} &= \frac{0.04}{D_*^{0.10}} & \text{if } 10 < D_* \leq 20 \\
 \theta_{cr} &= 0.013 D_*^{0.29} & \text{if } 20 < D_* \leq 150 \\
 \theta_{cr} &= 0.055 & \text{if } D_* > 150
 \end{aligned} \right\} \text{with } D_* = D_{50} \left(\frac{\Delta g}{\nu^2} \right)^{1/3} \quad (18)$$

Transport formula of Meyer-Peter and Müller (1984)

The empirical formula of Meyer-Peter and Müller (MP-M) for bed-load transport is written as

$$\Phi_s = 8(\psi - 0.047)^{3/2} \quad (19)$$

with $\mu = (C/C_{90})^{3/2}$ (ripple factor) (20)

$$\Phi_s = \frac{s}{D^{3/2} \sqrt{g\Delta}} \quad (\text{transport parameter}) \quad (21)$$

$$\psi = \mu\theta = \frac{\mu h i}{\Delta D_{50}} = \mu \frac{u^2}{C^2 \Delta D_{50}} \quad (\text{flow parameter}) \quad (22)$$

$$D = \bar{D} = \frac{\sum (p_i D_i)}{\sum p_i} \quad (23)$$

$$C_{90} = 18 \cdot \log(12 h / D_{90}) \quad (24)$$

i = energy gradient (bed gradient in case of uniform flow conditions)

s = bed-load transport per unit of width (without pores, otherwise multiply with

$$1/(1-\varepsilon_p) \approx 1.66)$$

It is valid for situations in which $w_s/u_* > 1$, $D_m > 0.4$ mm, and $\mu\theta < 0.2$.

For the MP-M formula an approximate power function $s = m u^n$ can be defined, with n equal to

$$n = \frac{3}{1 - 0.047 \Psi^{-1}} \quad (25)$$

Note: can only be used if C -value is known.

Transport formula of Engelund and Hansen (1967)

The formula of Engelund and Hansen (1967) for total load (bed- and suspended bed-material load) is written as:

$$\phi_s = 0.05 \Psi^{5/2} \quad (26)$$

with
$$\mu = \left(C^2 / g \right)^{2/5} \quad (\text{ripple factor}) \quad (27)$$

$$\Phi_s = \frac{s}{D_{50}^{3/2} \sqrt{g \Delta}} \quad (\text{transport parameter}) \quad (\text{cf. eq. 21})$$

$$\psi = \mu \theta = \frac{\mu h i}{\Delta D_{50}} \quad (\text{flow parameter}) \quad (\text{cf. eq. 22})$$

i = energy gradient (bed gradient in case of uniform flow conditions)

s = bed-load transport per unit of width (without pores, otherwise multiply with $1/(1-\varepsilon_p) \approx 1.66$)

The formula can also be written as (useful for unsteady flow):

$$s = 0.05 \sqrt{g \Delta D_{50}^3} \left(\frac{u_*}{\sqrt{g \Delta D_{50}}} \right)^3 \left(\frac{u}{\sqrt{g \Delta D_{50}}} \right)^2 = 0.05 \frac{u^5}{\sqrt{g C^3 \Delta^2 D_{50}}} \quad (28)$$

Engelund and Hansen is valid for situations in which $w_s/u_* < 1$, $0.19 < D_{50} < 0.93$ mm, and

$0.07 < \theta < 6$.

Transport formula of van Rijn (1984)

The transport formula of van Rijn (1984) distinguishes between a bed-load part (s_b) and a suspended-load part (s_s):

$$s = s_b + s_s \quad (29)$$

A transport stage parameter T is defined as:

$$T = \frac{\tau'_b - \tau_{b\ cr}}{\tau_{b\ cr}} = \frac{(C/C')^2 \theta - \theta_{cr}}{\theta_{cr}} \quad (30)$$

with

$$\begin{aligned} \tau'_b &= \text{bed-shear related to grains} \\ \tau_{b\ cr} &= \text{critical bed-shear according to the Shields curve} \end{aligned}$$

Bed-shear τ'_b is written, with $C=C_{90}$ (see Meyer-Peter and Müller) as

$$\tau'_b = \left(\frac{C}{C'} \right)^2 \tau_b \quad (31)$$

A dimensionless particle parameter D_* is defined as

$$D_* = D_{50} \left(\frac{\Delta g}{\nu^2} \right)^{\frac{1}{3}} \quad (32)$$

Bed-load transport then follows from

$$\begin{aligned} \Phi_b &= 0.053 \frac{T^{2.1}}{D_*^{0.3}} \text{ voor } T < 3 \\ \Phi_b &= 0.1 \frac{T^{1.5}}{D_*^{0.3}} \text{ voor } T \geq 3 \end{aligned} \quad (33)$$

with a transport parameter

$$\Phi_b = \frac{s_b}{\sqrt{g \Delta D_{50}^3}} \quad (34)$$

and s_b is bed-load transport without pores, particles in the range 200-2000 μm .

Suspended-load transport then follows from

$$s_s = F u h c_a \quad (35)$$

with

u = depth-averaged flow velocity

h = water depth

F = integration factor

C_a = reference concentration at level a measured from the bed

a = reference level, assumed to be $1/2 \cdot \text{bed-form-height}$ or equal to equivalent roughness height k_s , with minimum value $0.01 \cdot h$.

The reference concentration c_a (excluding pores) is written as

$$c_a = 0.015 \frac{D_{50} T^{1.5}}{a D_*^{0.3}} \quad (36)$$

And the integration factor F is written as:

$$F = \frac{\left(\frac{a}{h}\right)^{Z'} - \left(\frac{a}{h}\right)^{1.2}}{\left(1 - \frac{a}{h}\right)^{Z'} (1.2 - Z')} \quad (37)$$

in which

$$Z' = \frac{w_s}{\left(1 + 2 \left(\frac{w_s}{u_*}\right)^2\right) \kappa u_*} + 2.5 \left(\frac{w_s}{u_*}\right)^{0.8} \left(\frac{c_a}{0.65}\right)^{0.4} \quad \text{for } 0.01 \leq \frac{w_s}{u_*} \leq 1 \quad (38)$$

Where κ = constant of Von Karman (=0.4). The fall velocity w_s is computed (using equations 14 to 16) from the representative grain size of suspended sediment D_s , following from

$$\frac{D_s}{D_{50}} = 1 + 0.011 \left(\frac{1}{2} \left(\frac{D_{84}}{D_{50}} + \frac{D_{50}}{D_{16}} \right) - 1 \right) (T - 25) \quad (39)$$

Transport formula of Ackers and White (1973)

The formula of Ackers and White (1973) starts from the definition of D_{gr} :

$$D_{gr} = D_{35} \left[\frac{g \Delta}{v^2} \right]^{1/3} \quad (40)$$

for coarse sediment, which is only considered here if $D_{gr} > 60$.

Then can be deduced that

$$G_{gr} = 0.025 \left[\frac{F_{gr}}{0.17} - 1 \right]^{1.5} \quad (41)$$

with

$$F_{gr} = \frac{1}{\sqrt{g\Delta D_{35}}} \frac{u}{\sqrt{32} \log \frac{10h}{D_{35}}} \quad (42)$$

and

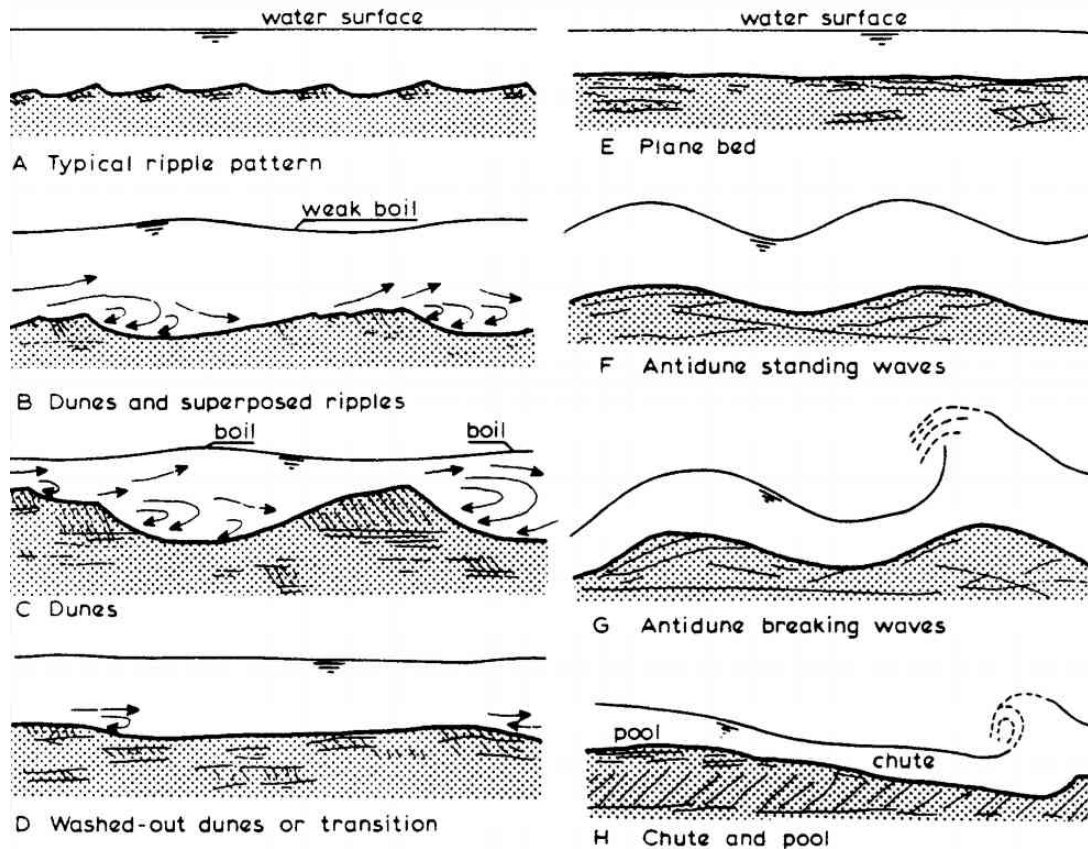
$$X_* = \frac{(\Delta + 1)D_{35} G_{35}}{h} \left\{ \frac{C}{\sqrt{g}} \right\} \quad (43)$$

and finally

$$s = \frac{X_* q \rho}{\rho_s (1 - \varepsilon)} \quad \text{met } \varepsilon \approx 0.4 \quad (44)$$

4. Bed forms and alluvial roughness

Types and classification are shown below:



Flow regime	Bedform	Bed-material concentration (ppm)	Mode of sediment transport	Type of roughness	Roughness $\frac{C}{\sqrt{g}}$
Lower regime	Ripples	10 – 200	Discrete steps	Form roughness predominate	7.8 – 12.4
	Ripples on dunes	100 – 1,200			7.0 – 13.2
	Dunes	200 – 2,000			
Transition	Washed-out dunes	1,000 – 3,000		Variable	7.0 – 20.2
Upper regime	Plane bed	2,000 – 6,000	continuum	Grain-roughness predominates	16.3 – 20
	Antidunes	> 2,000			10.3 - 20
	Chutes and pools	> 2,000			9.4 – 10.7

Alluvial roughness predictor of White c.s (1980)

The roughness predictor of White C.S. (1980), here only presented for coarse material ($D_{gr} = D_{35}[g\Delta v^2]^{1/3} > 60$), follows an iteration procedure. Given is bed slope i , a discharge per unit of width q , grain characteristics (ρ_s and D_{35}), and fluid characteristics (ρ and v). The water depth (h) is estimated, from which can be computed that $u_* = \sqrt{ghi}$.

This results in

$$F_{fg} = \frac{u^*}{\sqrt{g\Delta D}} \quad (45)$$

Then determine F_{gr} from:

$$\frac{F_{gr} - 0.17}{F_{fg} - 0.17} = 1.0 - 0.76 \left[1.0 - \frac{1}{\exp\left\{\left[\log D_{gr}\right]^{1.7}\right\}} \right] \quad (46)$$

Compute the flow velocity u from

$$F_{gr} = \frac{1}{\sqrt{g\Delta D}} \frac{u}{\sqrt{32 \cdot \log\{10h/D\}}} \quad (47)$$

Make an improved estimate for the depth $h=q/u$ until h is sufficiently accurate.

Compute C from

$$C = \frac{u}{u^*} \sqrt{g} = \frac{u}{\sqrt{hi}} \quad (48)$$

τ in a component due to bed forms (τ'') and a component due to roughness of sediment particles (τ'). Hence,

$$hi = (hi)'' + (hi)' \quad (49)$$

with $i = i'' = i'$, the depth (h) is subdivided into h'' and h' .

In 1967 Engelund and Hansen propose (with $\psi' = h''i / \Delta D$ en $\psi = hi / \Delta D$):

$$\Psi' = 0.06 + 0.4\Psi^2 \quad (50)$$

However, based on measurements, Engelund and Fredsøe (1982) propose:

$$\Psi' = 0.06 + 0.3\Psi^{3/2} \quad (51)$$

With given q , i , Δ and D the iteration procedures is as follows:

- (i) Estimate u , after which h' can be computed from

$$\frac{u}{u_*'} = \frac{u}{\sqrt{g'hi}} = 9.45 \left\{ \frac{h'}{k} \right\}^{1/8} \quad (52)$$

i.e., for roughness without bed forms.

Recommended value for $k = 2.5 \cdot D_s$ (sedimentation diameter).

- (ii) Determine $\psi' = h''i / \Delta D$

- (iii) Determine ψ from eq. (50) or (51) respectively. From ψ follows h .

- (iv) Make an improvement estimation of u from $q = u \cdot h$ and repeat the procedure.
- (v) With $u = C\sqrt{hi}$ the resulting C -value can then be determined.

Roughness predictor of Van Rijn (1987)

The bed form height H can be estimated from the following equation:

$$H = 0.11 h \left(\frac{D_{50}}{h} \right)^{0.3} (1 - e^{-0.5T})(25 - T) \quad \text{if } 0 < T < 25 \quad (53)$$

$$H = 0 \quad \text{if } T \leq 0 \quad \text{or } T \geq 25$$

In which:

$$T = \text{transport stage parameter, defined by equation (30)}$$

$$h = \text{water depth}$$

Furthermore, the bed form length L can be defined as:

$$L = 7.3 h \quad (54)$$

Based on these formulés the total equivalent Nikuradse roughness height k_s is defined by van Rijn as:

$$k_s = k'_s + 1.1H \left(1 - e^{-\frac{25H}{L}} \right) \quad (55)$$

In which

$$k'_s = 3 D_{90} \text{ is the equivalent Nikuradse roughness height of grains.}$$

Using the equivalent Nikuradse roughness height the Chézy coefficient for total roughness becomes

$$C = 18 \log \left(\frac{12 h}{k_s} \right) \quad (56)$$

5. Morphological time scales and celerities

The celerities express the propagation speed of small disturbances (infinitely small waves) on the water surface or on the bed. For the one-dimensional equations three celerities can be deduced:

- a negative and a positive celerity ($c_{1,2}$) associated to the propagation of long waves on the water surface ($\approx u \pm \sqrt{gh}$)
- a positive celerity associated to the propagation of small bed-waves, with an approximate value:

$$c_3 = (u_m \psi) / (1 - Fr^2) \quad \text{where } \psi = \frac{ds/du}{h} \approx n \cdot \frac{s}{q} \quad (57)$$

with Fr = Froude number of the main-channel flow, h = average water depth in main channel, q = main-channel discharge per unit of width, s = sediment-transport rate per unit of width, u_m = flow velocity in main channel, n = power of the transport formula (if $s = mu^n$).

Theoretically the morphological time-scale T is defined as

$$T = \varepsilon \frac{L \cdot h}{s} \quad (58)$$

With ε = definition factor dependent on the actual time-scale definition, with an order of magnitude of 1.0; and L = characteristic length scale.

Different types of phenomena are usually considered for definition of the time scale:

- Wave propagation: for small length scales hydraulic roughness is negligible, and morphological changes have a wave-character. The propagation speed of the wave (with small amplitude) is defined as:

$$c = \frac{u \left(\frac{ds}{du} \right)}{h(1 - Fr^2)} = \frac{n \cdot s}{h(1 - Fr^2)} \quad (59)$$

With n = non-linearity of the transport formula (e.g., see formula 25), and Fr is the Froude number. The time scale T_g is defined as the time in which the wave propagates of a distance L_g :

$$T_g = \frac{L_g}{c} = \frac{L_g h (1 - Fr^2)}{n \cdot s} \quad (60)$$

- Diffusion: for changes over long lengths ($L_d > \{2 \text{ to } 3\} \cdot h/i$) the bed-profile development has a diffusion character with a diffusion coefficient

$$D = \frac{u \left(\frac{ds}{du} \right)}{3i} = \frac{n \cdot s}{3i} \quad (61)$$

With i = slope. The time scale T_d is defined as the time in which, at a distance L_d upstream of a measure, 50 % of the final erosion or sedimentation due to this measure has occurred

$$T_d = \frac{L_d^2}{D} = \frac{3L_d^2 \cdot i}{n \cdot s} \quad (62)$$

- Relaxation of 2D (depth-averaged) processes: for processes that adapt gradually to an equilibrium condition, resulting in a diffusion-type of adaptation of the 2D morphology. The time-scale T_{2D} is defined as the time in which along one bank 50% of the total erosion or sedimentation occurs, caused by a measure taken on the other bend. It is written as:

$$T_{2D} = \frac{B^2 f(\theta)}{\pi^2 s} = \frac{\lambda_s h}{s} \quad (63)$$

Where B = river width, $f(\theta)$ = function of the Shields parameter which expresses the effect of transverse bed-slope on the direction of sediment transport (see section 6), and λ_s = adaptation length for 2D morphology according to Struiksma et al (1985), defined as:

$$\lambda_s = \frac{f(\theta)}{\pi^2} \left(\frac{B}{h} \right) B \quad (64)$$

6. Two-dimensional (2D) morphology

Due to curvature of flow (in river bends) the morphology is determined by near-bed flow deflection by helical flow and by gravity effects on particles by transverse slope. These effects are reproduced by correcting the sediment-transport direction as follows:

$$\tan(\beta) = \frac{\sin(\alpha) - f(\theta, \eta)^{-1} \frac{\partial z}{\partial \eta}}{\sin(\alpha) - f(\theta, \xi)^{-1} \frac{\partial z}{\partial \xi}} \quad (65)$$

In which $\partial z / \partial \eta$ and $\partial z / \partial \xi$ are bed-level slope in transverse (η) and in flow (ξ) direction respectively, and $f(\theta)$ = function of the Shields parameter which expresses the effect of transverse bed-slope on the direction of sediment transport.

In river bend redistribution of flow and sediment occur, which leads to an axi-symmetric solution in a long bend (or a bend with strongly damped morphology) with constant radius. The transverse bed slope β of the axi-symmetric situation is defined as:

$$\tan(\beta) = A f(\theta) \frac{h}{R} \quad (66)$$

In which R = radius of curvature of the bend flow, and A = spiral flow coefficient defined as:

$$A = \frac{2\varepsilon}{\kappa^2} \left(1 - \frac{\sqrt{g}}{\kappa C} \right) \quad (67)$$

Where ε = calibration factor (≈ -1), κ = Von Karman coefficient (≈ 0.4), g = gravity acceleration, and C = Chézy value. The function $f(\theta)$ was defined by Talmon et al (1995) as:

$$f(\theta) = 9 \left(\frac{D}{h} \right)^{0.3} \sqrt{\theta} \quad (68)$$

In practice often the function is written as $f(\theta) = 0.85\sqrt{\theta}$ for natural channels (or about $1.7\sqrt{\theta}$ for laboratory flumes).

The shape of a point bar in river bend is determined by the wave length L_p and damping length L_D expressed by Struiksma et al (1985) as:

$$2\pi \frac{\lambda_w}{L_p} = \frac{1}{2} \sqrt{(n+1)IP^{-1} - IP^{-2} - \left(\frac{n-3}{2}\right)^2} \quad (68)$$

$$\frac{\lambda_w}{L_D} = \frac{1}{2} \left(IP^{-1} - \frac{n-3}{2} \right) \quad (69)$$

Where n = non-linearity of the transport formula (e.g., see formula 25), λ_w = adaptation length for 2D flow, defined as $\lambda_w = C^2 h / (2g)$, λ_s = adaptation length for 2D morphology according to Struiksma et al (1985), defined as equation 64. IP is the interaction parameter defined as:

$$IP = \frac{\lambda_s}{\lambda_w} \approx 2 \frac{g}{C^2} \left(\frac{B}{h} \right)^2 \left(\frac{D}{h} \right)^{0.3} \sqrt{\theta} \quad (70)$$